

LIST OF POSSIBLY USEFUL FORMULAS

$$\epsilon_0 = 8.85 \times 10^{-12} \text{ C}^2 / \text{N.m}^2$$

$$k_e = 8.99 \times 10^9 \text{ N.m}^2 / \text{C}^2$$

$$e = -1.6 \times 10^{-19} \text{ C}$$

$$\oint \vec{E} \cdot d\vec{A} = \frac{q_{in}}{\epsilon_0}$$

$$\oint \vec{B} \cdot d\vec{A} = 0$$

$$\oint \vec{E} \cdot d\vec{s} = -\frac{d\Phi_B}{dt}$$

$$\oint \vec{B} \cdot d\vec{s} = \mu_0 I + \mu_0 \epsilon_0 \frac{d\Phi_E}{dt}$$

$$\vec{F} = q\vec{v} \times \vec{B} + q\vec{E}$$

$$\Phi_E = \int \vec{E} \cdot d\vec{A}$$

$$\Delta V = -\int_i^f \vec{E} \cdot d\vec{s}$$

$$C = \frac{Q}{\Delta V}$$

$$C = \epsilon_0 \frac{A}{d}$$

$$C = \kappa C_0$$

$$U = \frac{Q^2}{2C}$$

$$I = \frac{dq}{dt}$$

$$R = \frac{V}{I}$$

$$r = \frac{mv}{qB}$$

$$\vec{F} = I\vec{L} \times \vec{B}$$

$$\vec{\tau} = I\vec{A} \times \vec{B}$$

$$B = \frac{\mu_0 I}{2\pi r} \text{ for a long, straight wire}$$

$$B = \frac{\mu_0 I \phi}{4\pi r} \text{ for a circular arc of wire}$$

$$m_e = 9.11 \times 10^{-31} \text{ kg}$$

$$\mu_0 = 4\pi \times 10^{-7} \text{ T.m/A}$$

$$c = 3 \times 10^8 \text{ m/s}$$

$$B = \mu_0 nI \text{ for a solenoid}$$

$$B = \frac{\mu_0 NI}{2\pi r} \text{ for a toroid}$$

$$\Phi_B = \int \vec{B} \cdot d\vec{A}$$

$$\mathcal{E} = -N \frac{d\Phi_B}{dt}$$

$$c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

$$k = \frac{2\pi}{\lambda}$$

$$\omega = 2\pi f$$

$$\lambda f = c$$

$$\frac{E}{B} = \frac{E_{\max}}{B_{\max}} = c$$

$$\vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B}$$

$$\theta_i = \theta_{\text{refl}}$$

$$n_1 \sin \theta_1 = n_2 \sin \theta_2$$

$$n = \frac{c}{v}$$

$$\lambda_n = \frac{\lambda}{n}$$

$$\sin \theta_c = \frac{n_2}{n_1}$$

$$M \equiv \frac{h'}{h} = -\frac{q}{p}$$

$$\frac{1}{p} + \frac{1}{q} = \frac{1}{f}$$

$$f = \frac{R}{2} \text{ or } \frac{1}{f} = (n-1) \left(\frac{1}{R_1} - \frac{1}{R_2} \right)$$

$$\phi = \frac{2\pi}{\lambda} \delta$$

$$\begin{aligned} \delta &= d \sin \theta \\ \delta_{\text{bright}} &= m\lambda \\ \delta_{\text{dark}} &= \left(m + \frac{1}{2}\right)\lambda \\ y_{\text{bright}} &= \frac{\lambda L}{d} m \\ y_{\text{dark}} &= \frac{\lambda L}{d} \left(\frac{1}{2} + m\right) \\ I &= I_{\text{max}} \cos^2\left(\frac{\phi}{2}\right) \end{aligned}, \quad m = 0, \pm 1, \pm 2, \dots$$

$$\begin{aligned} \delta &= 2nt \\ \delta &= \lambda m \text{ or } \delta = \left(m + \frac{1}{2}\right)\lambda, \quad m = 0, 1, 2, \dots \end{aligned}$$

$$\begin{aligned} \sin \theta &= \frac{m\lambda}{a} \\ y_m &\approx \frac{L}{a} \lambda m \\ I &= I_{\text{max}} \left[\frac{\sin(\pi a \sin \theta / \lambda)}{\pi a \sin \theta / \lambda} \right]^2 \end{aligned} \quad m = \pm 1, \pm 2, \pm 3, \dots$$

$$\begin{aligned} \theta_{\text{min}} &= \frac{\lambda}{a} \\ \theta_{\text{min}} &= 1.22 \frac{\lambda}{D} \\ d \sin \theta &= m\lambda \\ I &= \frac{I_0}{2} \text{ or } I = I_0 \cos^2 \theta \\ n &= \tan \theta_p \end{aligned}$$