

PHY 745 Group Theory
11-11:50 AM MWF Olin 102

Plan for Lecture 36:

- 1. Summary of what we learned about linear Lie groups, especially $SO(3)$ and $SU(2)$, their direct products and Clebsch-Gordan coefficients**
- 2. Review of topics in Group Theory**
- 3. Course evaluation**

Ref. J. F. Cornwell, *Group Theory in Physics, Vol I and II*, Academic Press (1984)


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23	Mon: 03/20/2017	Chap. 7.7	Jahn-Teller Effect	#15	03/24/2017
24	Wed: 03/22/2017	Chap. 7.7	Jahn-Teller Effect		
25	Fri: 03/24/2017		Spin 1/2	#16	03/27/2017
26	Mon: 03/27/2017		Dirac equation for H-like atoms	#17	03/29/2017
27	Wed: 03/29/2017	Chap. 14	Angular momenta	#18	03/31/2017
28	Fri: 03/31/2017	Chap. 16	Time reversal symmetry	#19	04/05/2017
29	Mon: 04/03/2017	Chap. 16	Magnetic point groups		
30	Wed: 04/05/2017	Literature	Topology and group theory in Bloch states	#20	04/07/2017
31	Fri: 04/07/2017		Introduction to Lie groups	#21	04/10/2017
32	Mon: 04/10/2017		Introduction to Lie groups		
33	Wed: 04/12/2017		Introduction to Lie groups		
	Fri: 04/14/2017		Good Friday Holiday -- no class		
34	Mon: 04/17/2017		Introduction to Lie groups		
35	Wed: 04/19/2017		Introduction to Lie groups		
36	Fri: 04/21/2017		Introduction to Lie groups		
	Mon: 04/24/2017		Presentations I	Jason and Ahmad	
	Wed: 04/26/2017		Presentations II	Taylor	


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DREST
Department of Physics


News



Visiting Assistant Professor
Opening in Physics



Part-time Instructor Opening in
Physics



Anaela Harter awarded NSF

Events

Fri, Apr. 21, 2017
Sodium Ion Electrolytes
Larry Rush, Jr.
MS. Defense
(Mentor: N. Holzwarth)
Public Talk:
Scales 009 at 12:30 PM

Fri, Apr. 21, 2017
SPS Picnic
5:30 PM on Olin Roof
(Olin 105, rain alternate)

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SO(3) – all continuous linear transformations in 3-dimensional space which preserve the length of coordinate vectors -- $R(\omega, \hat{n})$

SU(2) – all 2x2 unitary matrices $\mathbf{u}(\omega, \hat{n})$

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$$R(\omega, \hat{n}) = \begin{pmatrix} \cos \omega + n_3^2(1 - \cos \omega) & n_3 \sin \omega + n_1 n_2(1 - \cos \omega) & -n_2 \sin \omega + n_1 n_3(1 - \cos \omega) \\ -n_3 \sin \omega + n_1 n_2(1 - \cos \omega) & \cos \omega + n_2^2(1 - \cos \omega) & n_1 \sin \omega + n_2 n_3(1 - \cos \omega) \\ n_2 \sin \omega + n_1 n_3(1 - \cos \omega) & -n_1 \sin \omega + n_2 n_3(1 - \cos \omega) & \cos \omega + n_3^2(1 - \cos \omega) \end{pmatrix}$$

For example: $R(\omega, \hat{z}) = \begin{pmatrix} \cos \omega & \sin \omega & 0 \\ -\sin \omega & \cos \omega & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad -\pi < \omega \leq \pi$

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$$\mathbf{u}(\omega, \hat{n}) = \begin{pmatrix} \cos \frac{\omega}{2} + i n_3 \sin \frac{\omega}{2} & (i n_1 + n_2) \sin \frac{\omega}{2} \\ (i n_1 - n_2) \sin \frac{\omega}{2} & \cos \frac{\omega}{2} - i n_3 \sin \frac{\omega}{2} \end{pmatrix}$$

For example: $\mathbf{u}(\omega, \hat{z}) = \begin{pmatrix} e^{i\omega/2} & 0 \\ 0 & e^{-i\omega/2} \end{pmatrix} \quad -2\pi < \omega \leq 2\pi$

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Class structure of these groups

$$R(\omega, \hat{n}) = \begin{pmatrix} \cos \omega + n_3^2(1 - \cos \omega) & n_3 \sin \omega + n_1 n_2(1 - \cos \omega) & -n_2 \sin \omega + n_1 n_3(1 - \cos \omega) \\ -n_3 \sin \omega + n_1 n_2(1 - \cos \omega) & \cos \omega + n_2^2(1 - \cos \omega) & n_1 \sin \omega + n_2 n_3(1 - \cos \omega) \\ n_2 \sin \omega + n_1 n_3(1 - \cos \omega) & -n_1 \sin \omega + n_2 n_3(1 - \cos \omega) & \cos \omega + n_1^2(1 - \cos \omega) \end{pmatrix}$$

$\text{Tr}(R(\omega, \hat{n})) = 3 \cos \omega + (n_1^2 + n_2^2 + n_3^2)(1 - \cos \omega) = 1 + 2 \cos \omega \Rightarrow$ depends on $|\omega|$ and not on \hat{n}

$$\mathbf{u}(\omega, \hat{n}) = \begin{pmatrix} \cos \frac{\omega}{2} + i n_3 \sin \frac{\omega}{2} & (i n_1 + n_2) \sin \frac{\omega}{2} \\ (i n_1 - n_2) \sin \frac{\omega}{2} & \cos \frac{\omega}{2} - i n_3 \sin \frac{\omega}{2} \end{pmatrix}$$

$\text{Tr}(\mathbf{u}(\omega, \hat{n})) = 2 \cos \frac{\omega}{2}$ depends on $|\omega|$ and not on \hat{n}

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“Generators” of the groups

$$R(\omega, \hat{n}) = \begin{pmatrix} \cos \omega + n_3^2(1 - \cos \omega) & n_3 \sin \omega + n_1 n_2(1 - \cos \omega) & -n_2 \sin \omega + n_1 n_3(1 - \cos \omega) \\ -n_3 \sin \omega + n_1 n_2(1 - \cos \omega) & \cos \omega + n_2^2(1 - \cos \omega) & n_1 \sin \omega + n_2 n_3(1 - \cos \omega) \\ n_2 \sin \omega + n_1 n_3(1 - \cos \omega) & -n_1 \sin \omega + n_2 n_3(1 - \cos \omega) & \cos \omega + n_1^2(1 - \cos \omega) \end{pmatrix}$$

$$\mathbf{a} = \lim_{\omega \rightarrow 0} \left(\frac{R(\omega, \hat{n}) - 1}{\omega} \right) = n_1 \mathbf{a}_1 + n_2 \mathbf{a}_2 + n_3 \mathbf{a}_3 = \begin{pmatrix} 0 & n_3 & -n_2 \\ -n_3 & 0 & n_1 \\ n_2 & -n_1 & 0 \end{pmatrix}$$

$$\mathbf{u}(\omega, \hat{n}) = \begin{pmatrix} \cos \frac{\omega}{2} + i n_3 \sin \frac{\omega}{2} & (i n_1 + n_2) \sin \frac{\omega}{2} \\ (i n_1 - n_2) \sin \frac{\omega}{2} & \cos \frac{\omega}{2} - i n_3 \sin \frac{\omega}{2} \end{pmatrix}$$

$$\mathbf{a} = \lim_{\omega \rightarrow 0} \left(\frac{\mathbf{u}(\omega, \hat{n}) - 1}{\omega} \right) = n_1 \mathbf{a}_1 + n_2 \mathbf{a}_2 + n_3 \mathbf{a}_3 = \frac{1}{2} \begin{pmatrix} i n_3 & i n_1 + n_2 \\ i n_1 - n_2 & -i n_3 \end{pmatrix}$$

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Irreducible representations of SO(3) and SU(2)
-- focusing on SU(2)

Consider the generator matrices

$$\mathbf{a} = \lim_{\omega \rightarrow 0} \left(\frac{\mathbf{u}(\omega, \hat{n}) - 1}{\omega} \right) = n_1 \mathbf{a}_1 + n_2 \mathbf{a}_2 + n_3 \mathbf{a}_3 = \frac{1}{2} \begin{pmatrix} i n_3 & i n_1 + n_2 \\ i n_1 - n_2 & -i n_3 \end{pmatrix}$$

$$\mathbf{a}_1 = \frac{1}{2} \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix} \quad \mathbf{a}_2 = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \quad \mathbf{a}_3 = \frac{1}{2} \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}$$

Commutation relations: $[\mathbf{a}_1, \mathbf{a}_2] = -\mathbf{a}_3$

In order to determine irreducible representations of SU(2), determine eigenstates associated with generators.

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Eigenfunctions associated with generator functions of SU(2)

$$\mathbf{a}_1 = \frac{1}{2} \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix} \quad \mathbf{a}_2 = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \quad \mathbf{a}_3 = \frac{1}{2} \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}$$

Commutation relations: $[\mathbf{a}_1, \mathbf{a}_2] = -\mathbf{a}_3$

It is convenient to map these generators into Hermitian matrices

$$\mathbf{A}_p \equiv -i\mathbf{a}_p = \frac{1}{2}\boldsymbol{\sigma}_p$$

$$\mathbf{A}_1 = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \mathbf{A}_2 = \frac{1}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad \mathbf{A}_3 = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Commutation relations: $[\mathbf{A}_1, \mathbf{A}_2] = i\mathbf{A}_3$

Define $\mathbf{A}^2 = \mathbf{A}_1^2 + \mathbf{A}_2^2 + \mathbf{A}_3^2 = \frac{3}{4} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

$$\mathbf{A}_- = \mathbf{A}_1 - i\mathbf{A}_2 = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \quad \mathbf{A}_+ = \mathbf{A}_1 + i\mathbf{A}_2 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

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Eigenfunctions associated with generator functions of SU(2)

Relationships between operators:

$$[\mathbf{A}^2, \mathbf{A}_p] = 0$$

$$\mathbf{A}_- \mathbf{A}_+ = \mathbf{A}^2 - \mathbf{A}_3^2 - \mathbf{A}_3$$

$$\mathbf{A}_+ \mathbf{A}_- = \mathbf{A}^2 - \mathbf{A}_3^2 + \mathbf{A}_3$$

Note that this "algebra" is identical to that of the total angular momentum operators

$$\mathbf{J}_x = \hbar\mathbf{A}_1 \quad \mathbf{J}_y = \hbar\mathbf{A}_2 \quad \mathbf{J}_z = \hbar\mathbf{A}_3$$

\Rightarrow Leap to eigenstates of \mathbf{J}^2 and \mathbf{J}_z : $|jm\rangle$

$$\mathbf{A}^2 |jm\rangle = j(j+1) |jm\rangle$$

$$\mathbf{A}_3 |jm\rangle = m |jm\rangle$$

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Eigenfunctions associated with generator functions of SU(2)

Additional relationships:

$$\mathbf{A}_- |jm\rangle = \{(j+m)(j-m+1)\}^{1/2} |j(m-1)\rangle$$

$$\mathbf{A}_+ |jm\rangle = \{(j-m)(j+m+1)\}^{1/2} |j(m+1)\rangle$$

Mapping the representations back to the original generators of SU(2): $\mathbf{a}_p = i\mathbf{A}_p$

$$D'_{mm'}(\mathbf{a}_p) \equiv \langle jm | \mathbf{a}_p | jm' \rangle$$

$$j=0 \quad D'_{mm'}(\mathbf{a}_p) = 0$$

$$j = \frac{1}{2} \quad D'_{mm'}(\mathbf{a}_1) = \frac{1}{2} \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix} \quad D'_{mm'}(\mathbf{a}_2) = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \quad D'_{mm'}(\mathbf{a}_3) = \frac{1}{2} \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}$$

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Comment of analogous equations for SO(3) --

Eigenfunctions associated with generator functions of SO(3)

$$R(\omega, \hat{n}) = \begin{pmatrix} \cos \omega + n_3^2(1 - \cos \omega) & n_1 \sin \omega + n_3 n_2(1 - \cos \omega) & -n_2 \sin \omega + n_3 n_1(1 - \cos \omega) \\ -n_1 \sin \omega + n_3 n_2(1 - \cos \omega) & \cos \omega + n_2^2(1 - \cos \omega) & n_1 \sin \omega + n_2 n_3(1 - \cos \omega) \\ n_2 \sin \omega + n_3 n_1(1 - \cos \omega) & -n_1 \sin \omega + n_2 n_3(1 - \cos \omega) & \cos \omega + n_1^2(1 - \cos \omega) \end{pmatrix}$$

$$\mathbf{a} = \lim_{\omega \rightarrow 0} \left(\frac{R(\omega, \hat{n}) - 1}{\omega} \right) = n_1 \mathbf{a}_1 + n_2 \mathbf{a}_2 + n_3 \mathbf{a}_3 = \begin{pmatrix} 0 & n_3 & -n_2 \\ -n_3 & 0 & n_1 \\ n_2 & -n_1 & 0 \end{pmatrix}$$

$$\mathbf{a}_1 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix} \quad \mathbf{a}_2 = \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} \quad \mathbf{a}_3 = \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$[\mathbf{a}_1, \mathbf{a}_2] = -\mathbf{a}_3$

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$$\mathbf{a}_1 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix} \quad \mathbf{a}_2 = \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} \quad \mathbf{a}_3 = \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Commutation relations: $[\mathbf{a}_1, \mathbf{a}_2] = -\mathbf{a}_3$

It is convenient to map these generators into Hermitian matrices

$$\mathbf{A}_p \equiv -i\mathbf{a}_p$$

$$\mathbf{A}_1 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix} \quad \mathbf{A}_2 = \begin{pmatrix} 0 & 0 & i \\ 0 & 0 & 0 \\ -i & 0 & 0 \end{pmatrix} \quad \mathbf{A}_3 = \begin{pmatrix} 0 & -i & 0 \\ i & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Commutation relations: $[\mathbf{A}_1, \mathbf{A}_2] = i\mathbf{A}_3$

Define $\mathbf{A}^2 = \mathbf{A}_1^2 + \mathbf{A}_2^2 + \mathbf{A}_3^2 = 2 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

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However, in this case \mathbf{A}_3 is not diagonal; using a similarity transformation:

$$\tilde{\mathbf{A}}_3 \equiv U^\dagger \mathbf{A}_3 U = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \end{pmatrix} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

$$\tilde{\mathbf{A}}_1 \equiv U^\dagger \mathbf{A}_1 U = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ 0 & \frac{1}{\sqrt{2}} & 0 \end{pmatrix}$$

$$\tilde{\mathbf{A}}_2 \equiv U^\dagger \mathbf{A}_2 U = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & -i \\ 0 & 0 & 0 \\ i & 0 & 0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ 0 & \frac{1}{\sqrt{2}} & 0 \end{pmatrix}$$

In accordance with the usual convention:

$\mathbf{J}_z = \hbar \tilde{\mathbf{A}}_3 \quad \mathbf{J}_y = \hbar \tilde{\mathbf{A}}_1 \quad \mathbf{J}_x = \hbar \tilde{\mathbf{A}}_2$

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In general, we can form a representation for SU(2) by evaluating $e^{\omega \mathbf{D}^i(\mathbf{a}_i)}$:

The character of this representation is

$$\chi^j(\omega) = \sum_{m=-j}^j e^{im\omega} = \frac{\sin\left(\left(j + \frac{1}{2}\right)\omega\right)}{\sin\left(\frac{1}{2}\omega\right)}$$

Direct product of irreducible representations \mathbf{D}^{j_1} and \mathbf{D}^{j_2}

It can be shown that $\mathbf{D}^{j_1 \otimes j_2} = \mathbf{D}^{j_1+j_2} \oplus \mathbf{D}^{j_1+j_2-1} \dots \mathbf{D}^{|j_1-j_2|}$

This follows from the character relationships:

$$\chi^{j_1 \otimes j_2}(\omega) = \frac{\sin\left(\left(j_1 + \frac{1}{2}\right)\omega\right)\sin\left(\left(j_2 + \frac{1}{2}\right)\omega\right)}{\sin^2\left(\frac{1}{2}\omega\right)} = \sum_{j=|j_1-j_2|}^{j_1+j_2} \chi^j(\omega)$$

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For example: $j_1=1/2$ and $j_2=1/2$

It can be shown that $\mathbf{D}^{j_1 \otimes j_2} = \mathbf{D}^{j_1+j_2} \oplus \mathbf{D}^{j_1+j_2-1} \dots \mathbf{D}^{|j_1-j_2|}$

This follows from the character relationships:

$$\chi^{1/2 \otimes 1/2}(\omega) = \chi^1(\omega) \oplus \chi^0(\omega)$$

$$\langle j_1 m_1 j_2 m_2 | j_1 j_2 j m \rangle = \langle \frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2} | \frac{1}{2} \frac{1}{2} 1 1 \rangle = 1$$

$$\langle \frac{1}{2} -\frac{1}{2} \frac{1}{2} \frac{1}{2} | \frac{1}{2} \frac{1}{2} 1 0 \rangle = \langle \frac{1}{2} \frac{1}{2} \frac{1}{2} -\frac{1}{2} | \frac{1}{2} \frac{1}{2} 1 0 \rangle = \frac{1}{\sqrt{2}}$$

$$\langle \frac{1}{2} -\frac{1}{2} \frac{1}{2} -\frac{1}{2} | \frac{1}{2} \frac{1}{2} 1 -1 \rangle = 1$$

$$\langle \frac{1}{2} -\frac{1}{2} \frac{1}{2} \frac{1}{2} | \frac{1}{2} \frac{1}{2} 0 0 \rangle = -\langle \frac{1}{2} \frac{1}{2} \frac{1}{2} -\frac{1}{2} | \frac{1}{2} \frac{1}{2} 0 0 \rangle = \frac{1}{\sqrt{2}}$$

Review --

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Group theory

An abstract algebraic construction in mathematics
Definition of a group:

A group is a collection of "elements" - A, B, C, \dots and a "multiplication" process. The abstract multiplication (\cdot) pairs two group elements, and associates the "result" with a third element. (For example $(A \cdot B = C)$.) The elements and the multiplication process must have the following properties.

1. The collection of elements is closed under multiplication. That is, if elements A and B are in the group and $A \cdot B = C$, element C must be in the group.
2. One of the members of the group is a "unit element" (E). That is, for any element A of the group, $A \cdot E = E \cdot A = A$.
3. For each element A of the group, there is another element A^{-1} which is its "inverse". That is $A \cdot A^{-1} = A^{-1} \cdot A = E$.
4. The multiplication process is "associative". That is for sequential multiplication of group elements A, B , and C , $(A \cdot B) \cdot C = A \cdot (B \cdot C)$.

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Definition:

An element $B \equiv XAX^{-1}$ is defined as conjugate to element A , where X is any element of the group.

Definition:

A class is composed of members of a group which are generated by the conjugate construction:

$\mathcal{C} = X_i^{-1}YX_i$ where Y is a fixed group element and X_i are all of the elements of the group.

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The great orthogonality theorem

Notation: $h \equiv$ order of the group

$R \equiv$ element of the group

$\Gamma^i(R)_{\alpha\beta} \equiv$ i th representation of R

$\mu\nu\alpha\beta$ denote matrix indices

$l_i \equiv$ dimension of the representation

$$\sum_R (\Gamma^i(R)_{\mu\nu})^* \Gamma^j(R)_{\alpha\beta} = \frac{h}{l_i} \delta_{ij} \delta_{\mu\alpha} \delta_{\nu\beta}$$

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Character of a representation:

$$\chi^j(R) = \sum_{\mu} \Gamma^j(R)_{\mu\mu}$$

In terms of classes \mathcal{C} , each with $N_{\mathcal{C}}$ elements:

$$\sum_{\mathcal{C}} N_{\mathcal{C}} (\chi^i(\mathcal{C}))^* \chi^j(\mathcal{C}) = h \delta_{ij}$$

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Some further conclusions:

$$\sum_{\mathbf{e}} N_{\mathbf{e}} (\chi^i(\mathbf{e}))^* \chi^j(\mathbf{e}) = h \delta_{ij}$$

The characters χ^i behave as a vector space with the dimension equal to the number of classes.

→ The number of characters = the number of classes

Second character identity:

$$\sum_i (\chi^i(\mathbf{e}_k))^* \chi^i(\mathbf{e}_l) = \frac{h}{N_{\mathbf{e}_k}} \delta_{kl}$$

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Example of character table for D_3

$D_3(32)$			E	$2C_3$	$3C_2'$
$x^2 + y^2, z^2$	R_z, z	A_1	1	1	1
		A_2	1	1	-1
(xz, yz)	(x, y)	E	2	-1	0
$(x^2 - y^2, xy)$					

↑
"Standard" notation for representations of D_3

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Extension of group notions to continuous groups

- Introduced notion of mapping group members to finite number of continuous parameters
- Introduced notion of "metric"
- Introduced notion of connected subgroups
- "Algebraic" properties of group generators

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