

**PHY 711 Classical Mechanics and
Mathematical Methods
10-10:50 AM MWF Olin 103**

Plan for Lecture 7:
Continue reading Chapter 3
**Further development of the
"calculus of variation"**


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Course schedule
(Preliminary schedule -- subject to frequent adjustment.)

Date	F&W Reading	Topic	Assignment
1 Wed, 8/29/2012	Chap. 1	Review of basic principles; Scattering theory	#1
2 Fri, 8/31/2012	Chap. 1	Scattering theory continued	#2
3 Mon, 9/03/2012	Chap. 1	Scattering theory continued	#3
4 Wed, 9/05/2012	Chap. 1 & 2	Scattering theory/Accelerated coordinate frame	#4
5 Fri, 9/07/2012	Chap. 2	Accelerated coordinate frame	#5
6 Mon, 9/10/2012	Chap. 3	Calculus of Variation	#6
7 Wed, 9/12/2012	Chap. 3	Calculus of Variation continued	

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Department of Physics

WFU Physics Colloquium

TITLE: "WFU Physics Research -- Part II"
TIME: Wednesday Sept. 12, 2012 at 4:00 PM
PLACE: George P. Williams, Jr. Lecture Hall, (Olin 101)

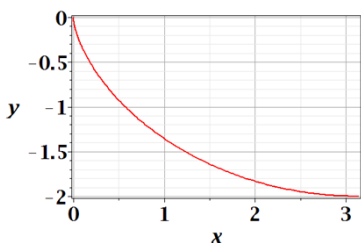
Refreshments will be served at 3:30 PM in the lounge. All interested persons are cordially invited to attend.

PROGRAM

This colloquium is the second of two which will highlight physics research at Wake Forest University. During the colloquium, Physics Department faculty members will present short overviews of their research programs in the Physics Department. This forum for sharing ideas will hopefully inspire collaborations between students and faculty and between research groups.

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Brachistochrone problem: (solved by Newton in 1696)
<http://mathworld.wolfram.com/BrachistochroneProblem.html>



A particle of weight mg travels frictionlessly down a path of shape $y(x)$. What is the shape of the path $y(x)$ that minimizes the travel time from $y(0)=0$ to $y(\pi)=-2$?

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$$T = \int_{x_1, y_1}^{x_2, y_2} \frac{ds}{v} = \int_{x_1}^{x_2} \frac{\sqrt{1 + \left(\frac{dy}{dx}\right)^2}}{\sqrt{-2gy}} dx \quad \text{because } \frac{1}{2}mv^2 = -mgy$$

$$f\left(y(x), \frac{dy}{dx}, x\right) = \frac{\sqrt{1 + \left(\frac{dy}{dx}\right)^2}}{-y}$$

Alternative relationships for extremization :

$$\left(\frac{\partial f}{\partial y}\right) - \frac{d}{dx} \left[\frac{\partial f}{\partial (dy/dx)} \right] = 0$$

$$\frac{d}{dx} \left(f - \frac{\partial f}{\partial (dy/dx)} \frac{dy}{dx} \right) = \left(\frac{\partial f}{\partial x} \right)$$

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$$f\left(\left\{y(x), \frac{dy}{dx}\right\}, x\right) = \sqrt{\frac{1 + \left(\frac{dy}{dx}\right)^2}{-y}}$$

$$\frac{d}{dx}\left(f - \frac{\partial f}{\partial(dy/dx)} \frac{dy}{dx}\right) = \left(\frac{\partial f}{\partial x}\right)$$

$$\Rightarrow \frac{d}{dx}\left(\frac{1}{\sqrt{-y\left(1 + \left(\frac{dy}{dx}\right)^2\right)}}\right) = 0 \quad -y\left(1 + \left(\frac{dy}{dx}\right)^2\right) = K \equiv 2a$$

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$$-y\left(1 + \left(\frac{dy}{dx}\right)^2\right) = K \equiv 2a \quad \text{Let } y = -2a \sin^2 \frac{\theta}{2} = a(\cos \theta - 1)$$

$$\frac{dy}{dx} = -\sqrt{\frac{2a}{-y} - 1} \quad -\frac{dy}{\sqrt{\frac{2a}{-y} - 1}} = \frac{2a \sin \frac{\theta}{2} \cos \frac{\theta}{2} d\theta}{\sqrt{2a \sin^2 \frac{\theta}{2} - 1}} = dx$$

$$-\frac{dy}{\sqrt{\frac{2a}{-y} - 1}} = dx \quad x = \int_0^\theta a(1 - \cos \theta') d\theta' = a(\theta - \sin \theta)$$

Parametric equations for Brachistochrone:

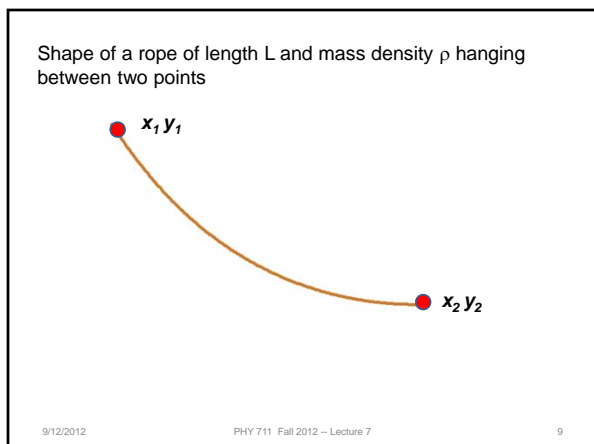
$$x = a(\theta - \sin \theta)$$

$$y = a(\cos \theta - 1)$$

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Potential energy of hanging rope :

$$E = \rho g \int_{x_1}^{x_2} y \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx$$

Length of rope :

$$L = \int_{x_1}^{x_2} \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx$$

Define a composite function to minimize :

$$W \equiv E + \lambda L$$

Lagrange multiplier

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$$W = \int_{x_1}^{x_2} (\rho g y + \lambda) \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx$$

$$f\left(y, \frac{dy}{dx}\right) = (\rho g y + \lambda) \sqrt{1 + \left(\frac{dy}{dx}\right)^2}$$

$$\frac{d}{dx} \left(f - \frac{\partial f}{\partial (dy/dx)} \frac{dy}{dx} \right) = \left(\frac{\partial f}{\partial x} \right)$$

$$\Rightarrow (\rho g y + \lambda) \left(\sqrt{1 + \left(\frac{dy}{dx}\right)^2} - \frac{\left(\frac{dy}{dx}\right)^2}{\sqrt{1 + \left(\frac{dy}{dx}\right)^2}} \right) = K$$

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$$(\rho g y + \lambda) \left(\sqrt{1 + \left(\frac{dy}{dx}\right)^2} - \frac{\left(\frac{dy}{dx}\right)^2}{\sqrt{1 + \left(\frac{dy}{dx}\right)^2}} \right) = K$$

$$(\rho g y + \lambda) \left(\frac{1}{\sqrt{1 + \left(\frac{dy}{dx}\right)^2}} \right) = K$$

$$y(x) = -\frac{1}{\rho g} \left(\lambda + K \cosh\left(\frac{x-a}{K/\rho g}\right) \right)$$

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$$y(x) = -\frac{1}{\rho g} \left(\lambda + K \cosh \left(\frac{x-a}{K/\rho g} \right) \right)$$

Integration constants : K, a, λ

Constraints : $y(x_1) = y_1$
 $y(x_2) = y_2$
 $\int_{x_1}^{x_2} \sqrt{1 + \left(\frac{dy}{dx} \right)^2} dx = L$

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Summary of results

For the class of problems where we need to perform an extremization on an integral form :

$$I = \int_{x_1}^{x_2} f \left(y(x), \frac{dy}{dx}, x \right) dx$$

A necessary condition is the Euler - Lagrange equations :

$$\left(\frac{\partial f}{\partial y} \right) - \frac{d}{dx} \left[\left(\frac{\partial f}{\partial (dy/dx)} \right) \right] = 0$$

$$\frac{d}{dx} \left(f - \frac{\partial f}{\partial (dy/dx)} \frac{dy}{dx} \right) = \left(\frac{\partial f}{\partial x} \right)$$

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Application to particle dynamics

$x \rightarrow t$ (time)
 $y \rightarrow q$ (generalized coordinate)
 $f \rightarrow L$ (Lagrangian)
 $I \rightarrow A$ (action)

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