PHY 711 Classical Mechanics and Mathematical Methods
10-10:50 AM MWF Olin 103

Plan for Lecture 11:

Continue reading Chapter 3 & 6

1. **Constants of the motion**
2. **Conserved quantities**

PHY 711 Classical Mechanics and Mathematical Methods

MWF 10 AM-10:50 PM	OPL 103	http://www.wfu.edu/~natalie/f12phy711/

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Course schedule

(Preliminary schedule -- subject to frequent adjustment.)

	Date	F&W Reading	Topic	Assignment
1	Wed, 8/29/2012	Chap. 1	Review of basic principles;Scattering theory	#1
2	Fri, 8/31/2012	Chap. 1	Scattering theory continued	#2
3	Mon, 9/03/2012	Chap. 1	Scattering theory continued	#3
4	Wed, 9/05/2012	Chap. 1 & 2	Scattering theory/Accelerated coordinate frame	#4
5	Fri, 9/07/2012	Chap. 2	Accelerated coordinate frame	#5
6	Mon, 9/10/2012	Chap. 3	Calculus of Variation	#6
7	Wed, 9/12/2012	Chap. 3	Calculus of Variation continued	
8	Fri, 9/14/2012	Chap. 3	Lagrangian	#7
9	Mon, 9/17/2012	Chap. 3 & 6	Lagrangian	#8
10	Wed, 9/19/2012	Chap. 3 & 6	Lagrangian	#9
11	Fri, 9/21/2012	Chap. 3 & 6	Lagrangian	#10

Summary of Lagrangian formalism (without constraints)

For independent generalized coordinates $q_\sigma(t)$:

$$L = L\left(\{q_\sigma(t)\}, \{\dot{q}_\sigma(t)\}, t\right)$$

$$\frac{d}{dt}\frac{\partial L}{\partial \dot{q}_\sigma} - \frac{\partial L}{\partial q_\sigma} = 0$$

Note that if $\frac{\partial L}{\partial q_\sigma} = 0$, then $\frac{d}{dt}\frac{\partial L}{\partial \dot{q}_\sigma} = 0$

$$\Rightarrow \frac{\partial L}{\partial \dot{q}_\sigma} = \text{(constant)}$$

Examples of constants of the motion:

Example 1: one-dimensional potential:

$$L = \tfrac{1}{2} m\left(\dot{x}^2 + \dot{y}^2 + \dot{z}^2\right) - V(z)$$

$$\Rightarrow \frac{d}{dt} m\dot{x} = 0 \qquad \Rightarrow m\dot{x} \equiv p_x \text{ (constant)}$$

$$\Rightarrow \frac{d}{dt} m\dot{y} = 0 \qquad \Rightarrow m\dot{y} \equiv p_y \text{ (constant)}$$

$$\Rightarrow \frac{d}{dt} m\dot{z} = -\frac{\partial V}{\partial z}$$

Examples of constants of the motion:

Example 2: Motion in a central potential

$$L = \tfrac{1}{2} m\left(\dot{r}^2 + r^2\dot{\phi}^2\right) - V(r)$$

$$\Rightarrow \frac{d}{dt} mr^2\dot{\phi} = 0 \qquad \Rightarrow mr^2\dot{\phi} \equiv p_\phi \ \ \text{(constant)}$$

$$\Rightarrow \frac{d}{dt} m\dot{r} = mr\dot{\phi}^2 - \frac{\partial V}{\partial r} = \frac{{p_\phi}^2}{mr^3} - \frac{\partial V}{\partial r}$$

Recall alternative form of Euler-Lagrange equations:

Starting from:

$$L = L\left(\{q_\sigma(t)\}, \{\dot{q}_\sigma(t)\}, t\right)$$

$$\frac{d}{dt}\frac{\partial L}{\partial \dot{q}_\sigma} - \frac{\partial L}{\partial q_\sigma} = 0$$

Also note that: $\frac{dL}{dt} = \sum_\sigma \frac{\partial L}{\partial q_\sigma}\dot{q}_\sigma + \sum_\sigma \frac{\partial L}{\partial \dot{q}_\sigma}\ddot{q}_\sigma + \frac{\partial L}{\partial t}$

$$= \frac{d}{dt}\left(\sum_\sigma \frac{\partial L}{\partial \dot{q}_\sigma}\dot{q}_\sigma\right) + \frac{\partial L}{\partial t}$$

$$\Rightarrow \frac{d}{dt}\left(L - \sum_\sigma \frac{\partial L}{\partial \dot{q}_\sigma}\dot{q}_\sigma\right) = \frac{\partial L}{\partial t}$$

Additional constant of the motion:

$$\text{If} \quad \frac{\partial L}{\partial t} = 0;$$

$$\text{then}: \quad \frac{d}{dt}\left(L - \sum_\sigma \frac{\partial L}{\partial \dot{q}_\sigma}\dot{q}_\sigma \right) = \frac{\partial L}{\partial t} = 0$$

$$\Rightarrow L - \sum_\sigma \frac{\partial L}{\partial \dot{q}_\sigma}\dot{q}_\sigma = -E \quad \text{(constant)}$$

Example 1: one-dimensional potential:

$$L = \tfrac{1}{2} m\left(\dot{x}^2 + \dot{y}^2 + \dot{z}^2\right) - V(z)$$

$$\Rightarrow \frac{d}{dt}\left(\tfrac{1}{2} m\left(\dot{x}^2 + \dot{y}^2 + \dot{z}^2\right) - V(z) - m\dot{x}^2 - m\dot{y}^2 - m\dot{z}^2\right) = 0$$

$$\Rightarrow -\left(\tfrac{1}{2} m\left(\dot{x}^2 + \dot{y}^2 + \dot{z}^2\right) + V(z)\right) = -E \quad \text{(constant)}$$

Additional constant of the motion -- continued:

$$\text{If} \quad \frac{\partial L}{\partial t} = 0;$$

$$\text{then}: \quad \frac{d}{dt}\left(L - \sum_\sigma \frac{\partial L}{\partial \dot{q}_\sigma} \dot{q}_\sigma \right) = \frac{\partial L}{\partial t} = 0$$

$$\Rightarrow L - \sum_\sigma \frac{\partial L}{\partial \dot{q}_\sigma} \dot{q}_\sigma = -E \quad \text{(constant)}$$

Example 2: Motion in a central potential

$$L = \tfrac{1}{2} m\left(\dot{r}^2 + r^2 \dot{\phi}^2\right) - V(r)$$

$$\Rightarrow \frac{d}{dt}\left(\tfrac{1}{2} m\left(\dot{r}^2 + r^2 \dot{\phi}^2\right) - V(r) - m\dot{r}^2 - m r^2 \dot{\phi}^2\right) = 0$$

$$\Rightarrow -\left(\tfrac{1}{2} m\left(\dot{r}^2 + r^2 \dot{\phi}^2\right) + V(r)\right) = -E \quad \text{(constant)}$$

Other examples

Lagrangian for symmetric top with Euler angles α, β, γ :

$$L = L(\alpha,\beta,\gamma,\dot{\alpha},\dot{\beta},\dot{\gamma}) = \tfrac{1}{2} I_1\left(\dot{\alpha}^2 \sin^2\beta + \dot{\beta}^2\right) + \tfrac{1}{2} I_3\left(\dot{\alpha}\cos\beta + \dot{\gamma}\right)^2$$

$$- Mgh\cos\beta$$

Constants of the motion :

$$\frac{\partial L}{\partial \gamma} = 0 \quad \Rightarrow \frac{d}{dt}\frac{\partial L}{\partial \dot{\gamma}} = 0 \qquad I_3\left(\dot{\alpha}\cos\beta + \dot{\gamma}\right) = p_\gamma \;\; \text{(constant)}$$

$$\frac{\partial L}{\partial \alpha} = 0 \quad \Rightarrow \frac{d}{dt}\frac{\partial L}{\partial \dot{\alpha}} = 0 \qquad I_1\dot{\alpha}\sin^2\beta + I_3\left(\dot{\alpha}\cos\beta + \dot{\gamma}\right)\cos\beta = p_\alpha \;\; \text{(constant)}$$

$$E = \sum_\sigma \frac{\partial L}{\partial \dot{q}_\sigma}\dot{q}_\sigma - L$$

$$= \tfrac{1}{2} I_1\left(\dot{\alpha}^2 \sin^2\beta + \dot{\beta}^2\right) + \tfrac{1}{2} I_3\left(\dot{\alpha}\cos\beta + \dot{\gamma}\right)^2 + Mgh\cos\beta$$

Other examples

$$L = \tfrac{1}{2} m\left(\dot{x}^2 + \dot{y}^2 + \dot{z}^2\right) + \frac{q}{2c} B_0\left(\dot{x}y - \dot{y}x\right)$$

$$\frac{\partial L}{\partial z} = 0 \qquad \Rightarrow m\dot{z} = p_z \quad \text{(constant)}$$

$$E = \sum_\sigma \frac{\partial L}{\partial \dot{q}_\sigma}\dot{q}_\sigma - L$$

$$= m\left(\dot{x}^2 + \dot{y}^2 + \dot{z}^2\right) + \frac{q}{2c} B_0\left(\dot{x}y - \dot{y}x\right)$$

$$- \tfrac{1}{2} m\left(\dot{x}^2 + \dot{y}^2 + \dot{z}^2\right) - \frac{q}{2c} B_0\left(\dot{x}y - \dot{y}x\right)$$

$$= \tfrac{1}{2} m\left(\dot{x}^2 + \dot{y}^2 + \dot{z}^2\right)$$

Lagrangian picture

For independent generalized coordinates $q_\sigma(t)$:

$$L = L\left(\{q_\sigma(t)\},\{\dot{q}_\sigma(t)\},t\right)$$

$$\frac{d}{dt}\frac{\partial L}{\partial \dot{q}_\sigma} - \frac{\partial L}{\partial q_\sigma} = 0$$

$\Rightarrow$ Second order differential equations for $q_\sigma(t)$

Switching variables – Legendre transformation

Mathematical transformations for continuous functions of several variables & Legendre transforms:

$$z(x,y) \quad \Leftrightarrow \quad x(y,z)???$$

$$z(x,y) \Rightarrow dz = \left(\frac{\partial z}{\partial x}\right)_y dx + \left(\frac{\partial z}{\partial y}\right)_x dy$$

$$x(y,z) \Rightarrow dx = \left(\frac{\partial x}{\partial y}\right)_z dy + \left(\frac{\partial x}{\partial z}\right)_y dz$$

$$\text{But:} \quad \left(\frac{\partial x}{\partial y}\right)_z = -\frac{\left(\partial z / \partial y\right)_x}{\left(\partial z / \partial x\right)_y}$$

Mathematical transformations for continuous functions of several variables & Legendre transforms continued:

$$z(x, y) \Rightarrow dz = \left(\frac{\partial z}{\partial x}\right)_y dx + \left(\frac{\partial z}{\partial y}\right)_x dy$$

$$\text{Let} \quad u \equiv \left(\frac{\partial z}{\partial x}\right)_y \quad \text{and} \quad v \equiv \left(\frac{\partial z}{\partial y}\right)_x$$

Define new function

$$w(u, y) \Rightarrow dw = \left(\frac{\partial w}{\partial u}\right)_y du + \left(\frac{\partial w}{\partial y}\right)_u dy$$

$$\text{For} \quad w = z - ux, \qquad dw = dz - udx - xdu = udx + vdy - udx - xdu$$

$$dw = -xdu + vdy \qquad \Rightarrow \left(\frac{\partial w}{\partial u}\right)_y = -x \qquad \left(\frac{\partial w}{\partial y}\right)_u = \left(\frac{\partial z}{\partial y}\right)_x = v$$

For thermodynamic functions:

$$\text{Internal energy:} \quad U = U(S,V)$$

$$dU = TdS - PdV$$

$$dU = \left(\frac{\partial U}{\partial S}\right)_V dS + \left(\frac{\partial U}{\partial V}\right)_S dV$$

$$\Rightarrow T = \left(\frac{\partial U}{\partial S}\right)_V \qquad P = -\left(\frac{\partial U}{\partial V}\right)_S$$

$$\text{Enthalpy:} \quad H = H(S,P) = U + PV$$

$$dH = dU + PdV + VdP = TdS + VdP = \left(\frac{\partial H}{\partial S}\right)_P dS + \left(\frac{\partial H}{\partial P}\right)_S dP$$

$$\Rightarrow T = \left(\frac{\partial H}{\partial S}\right)_P \qquad V = \left(\frac{\partial H}{\partial P}\right)_S$$

Name	Potential	Differential Form
Internal energy	$E(S,V,N)$	$dE = TdS - PdV + \mu dN$
Entropy	$S(E,V,N)$	$dS = \frac{1}{T}dE + \frac{P}{T}dV - \frac{\mu}{T}dN$
Enthalpy	$H(S,P,N) = E + PV$	$dH = TdS + VdP + \mu dN$
Helmholtz free energy	$F(T,V,N) = E - TS$	$dF = -SdT - PdV + \mu dN$
Gibbs free energy	$G(T,P,N) = F + PV$	$dG = -SdT + VdP + \mu dN$
Landau potential	$\Omega(T,V,\mu) = F - \mu N$	$d\Omega = -SdT - PdV - Nd\mu$

Lagrangian picture

For independent generalized coordinates $q_\sigma(t)$:

$$L = L\left(\{q_\sigma(t)\}, \{\dot{q}_\sigma(t)\}, t\right)$$

$$\frac{d}{dt}\frac{\partial L}{\partial \dot{q}_\sigma} - \frac{\partial L}{\partial q_\sigma} = 0$$

$\Rightarrow$ Second order differential equations for $q_\sigma(t)$

Switching variables – Legendre transformation

Define: $H = H\left(\{q_\sigma(t)\}, \{p_\sigma(t)\}, t\right)$

$$H = \sum_\sigma \dot{q}_\sigma p_\sigma - L \qquad \text{where } p_\sigma = \frac{\partial L}{\partial \dot{q}_\sigma}$$

$$dH = \sum_\sigma \left(\dot{q}_\sigma dp_\sigma + p_\sigma d\dot{q}_\sigma - \frac{\partial L}{\partial q_\sigma} dq_\sigma - \frac{\partial L}{\partial \dot{q}_\sigma} d\dot{q}_\sigma \right) - \frac{\partial L}{\partial t} dt$$

Hamiltonian picture – continued

$$H = H\left(\{q_\sigma(t)\},\{p_\sigma(t)\},t\right)$$

$$H = \sum_\sigma \dot{q}_\sigma p_\sigma - L \qquad \text{where} \quad p_\sigma = \frac{\partial L}{\partial \dot{q}_\sigma}$$

$$dH = \sum_\sigma \left(\dot{q}_\sigma dp_\sigma + p_\sigma d\dot{q}_\sigma - \frac{\partial L}{\partial q_\sigma} dq_\sigma - \frac{\partial L}{\partial \dot{q}_\sigma} d\dot{q}_\sigma \right) - \frac{\partial L}{\partial t} dt$$

$$= \sum_\sigma \left(\frac{\partial H}{\partial q_\sigma} dq_\sigma + \frac{\partial H}{\partial p_\sigma} dp_\sigma \right) + \frac{\partial H}{\partial t} dt$$

$$\Rightarrow \dot{q}_\sigma = \frac{\partial H}{\partial p_\sigma} \qquad \frac{\partial L}{\partial q_\sigma} = \frac{d}{dt} \frac{\partial L}{\partial \dot{q}_\sigma} \equiv \dot{p}_\sigma = -\frac{\partial H}{\partial q_\sigma} \qquad \frac{\partial L}{\partial t} = -\frac{\partial H}{\partial t}$$